

# Damping Ring Kicker Tests at AØ

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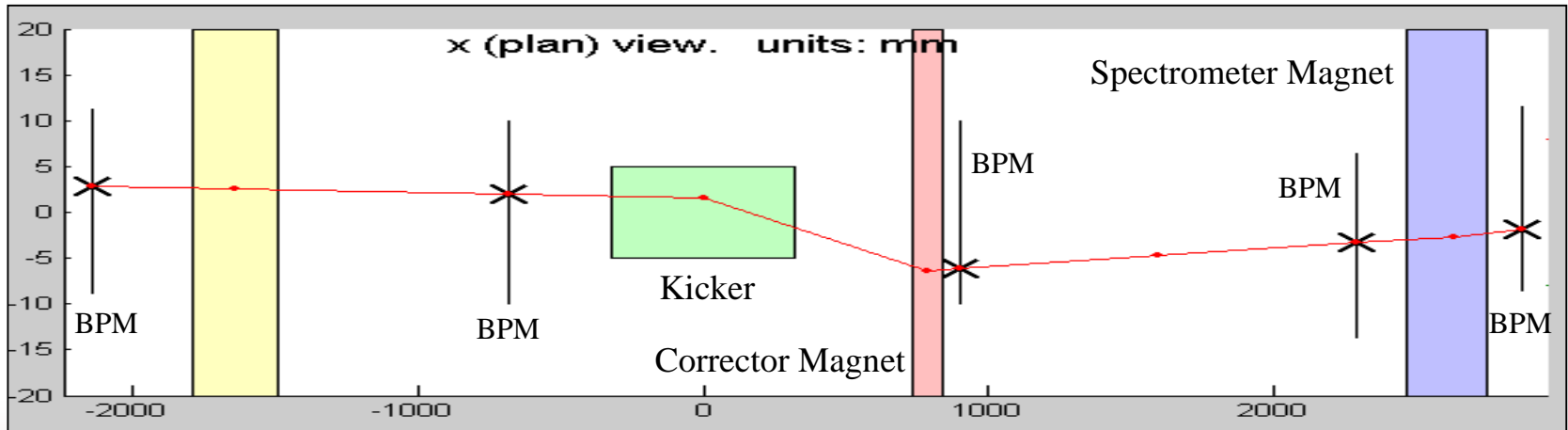
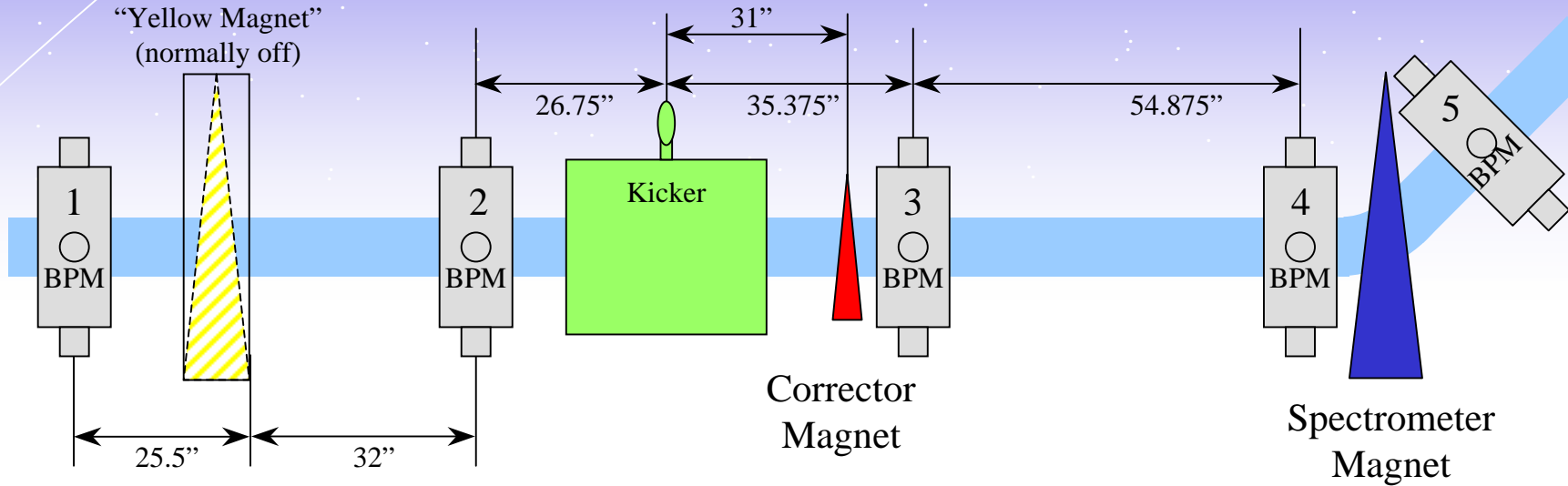
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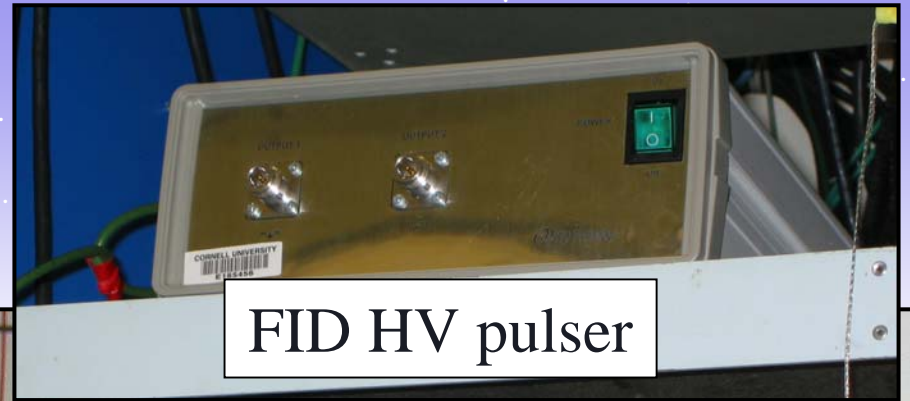
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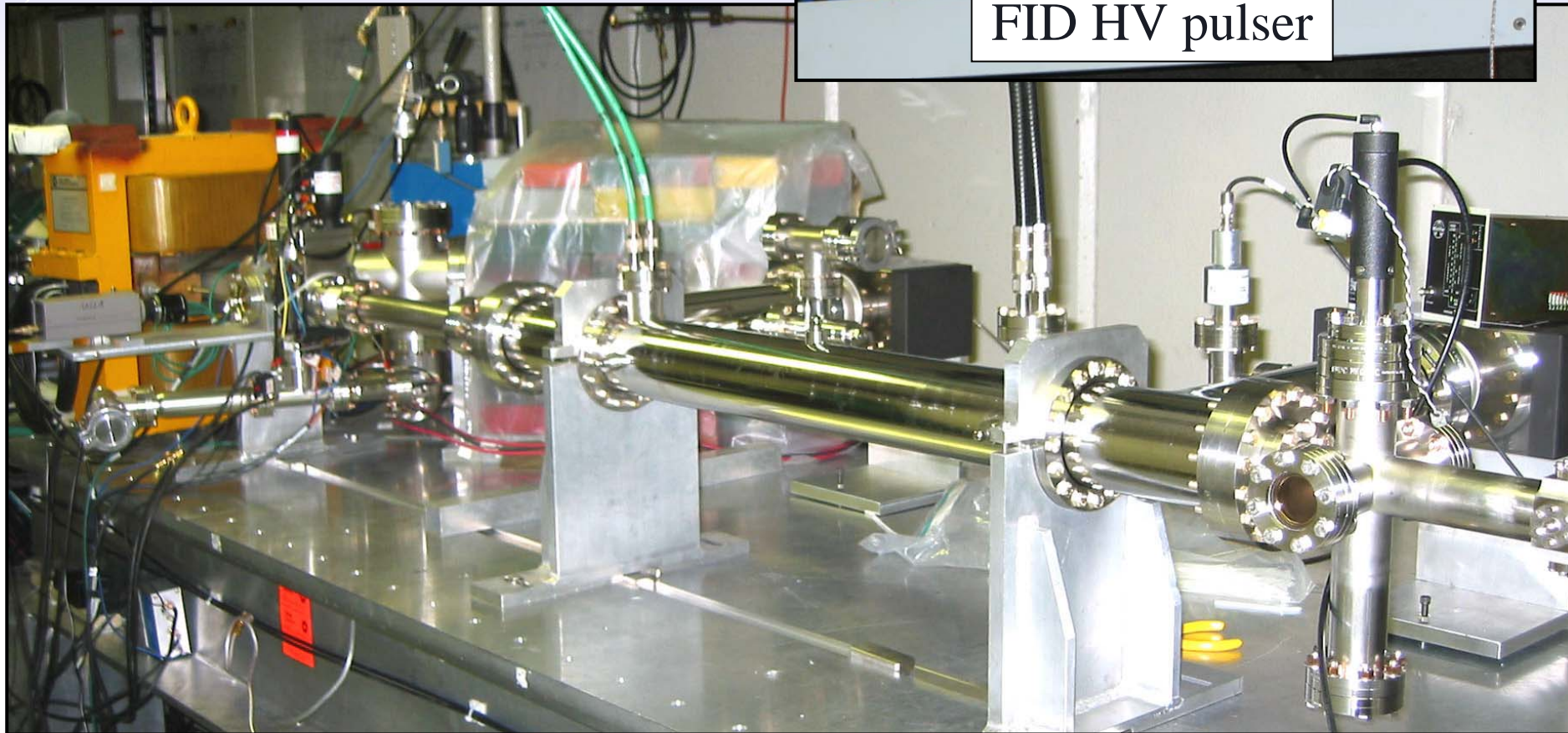
# Kicker and AØ 16 MeV electron beam layout



# Kicker installed at AØ



FID HV pulser



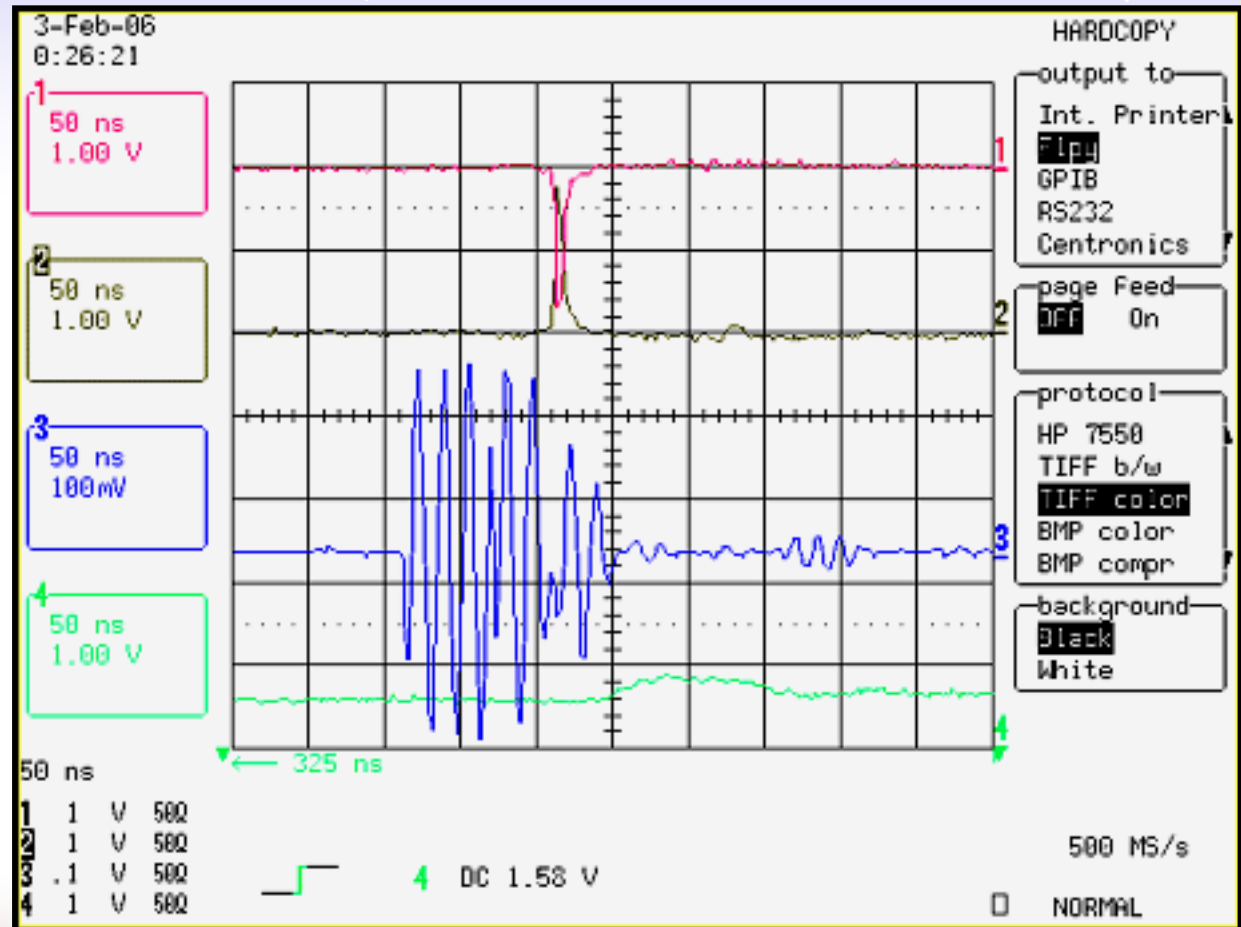
# Data

BPM information read by DAQ, written directly to event data record.

$\pm$ FID pulses digitized after leaving the kicker and passing through soft cables.

Phase detector signal mixed with 1.3 GHz RF, then digitized.

500 MHz scope data read, then written to event record.

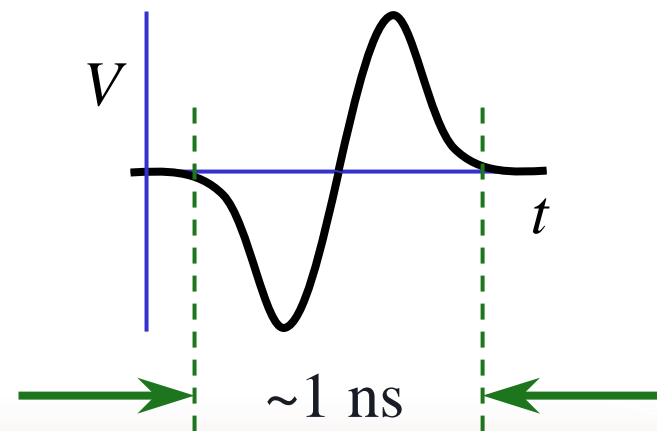


# Phase detector: precision measurement of bunch arrival time

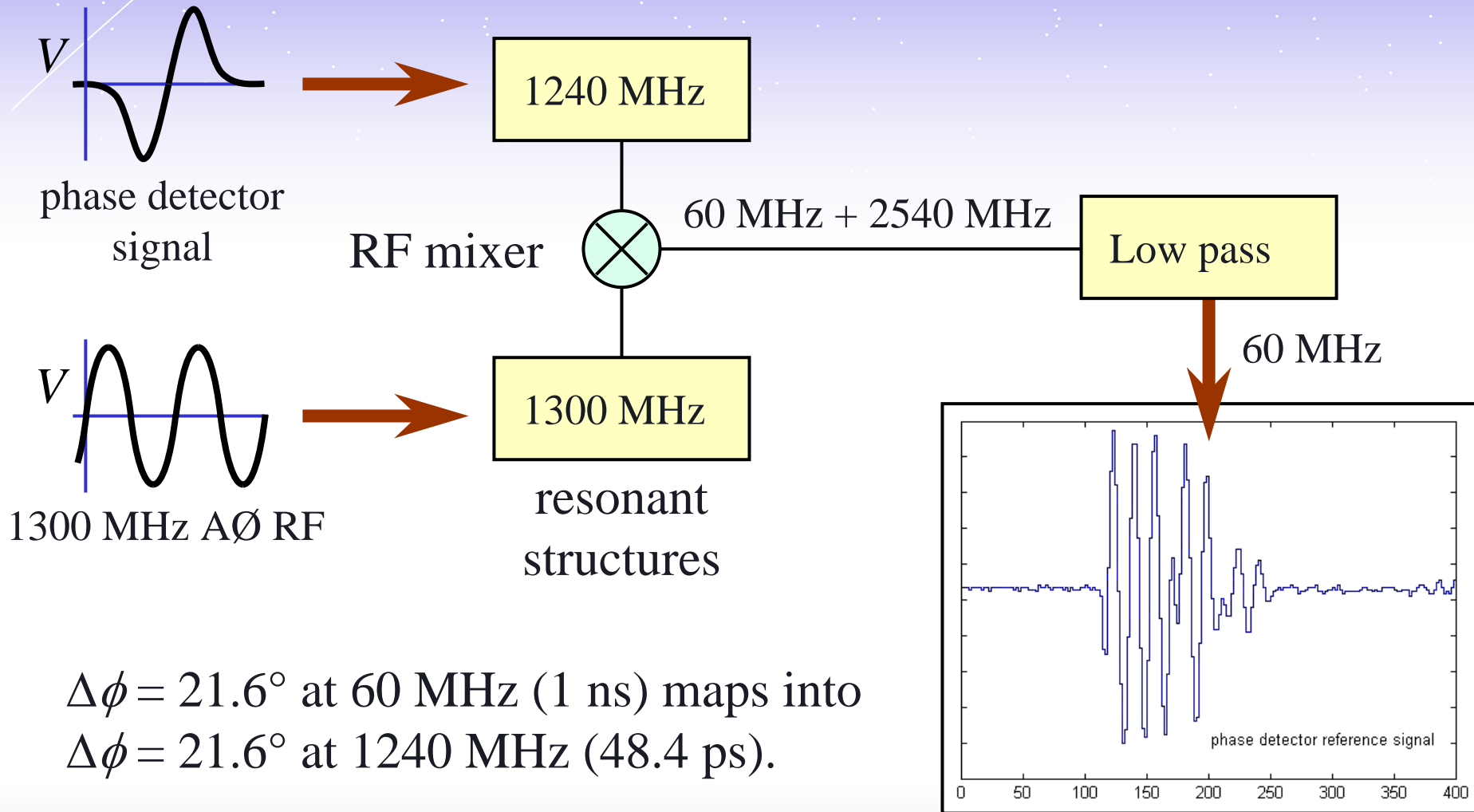


The device produces a very short bipolar signal when a bunch passes through it.

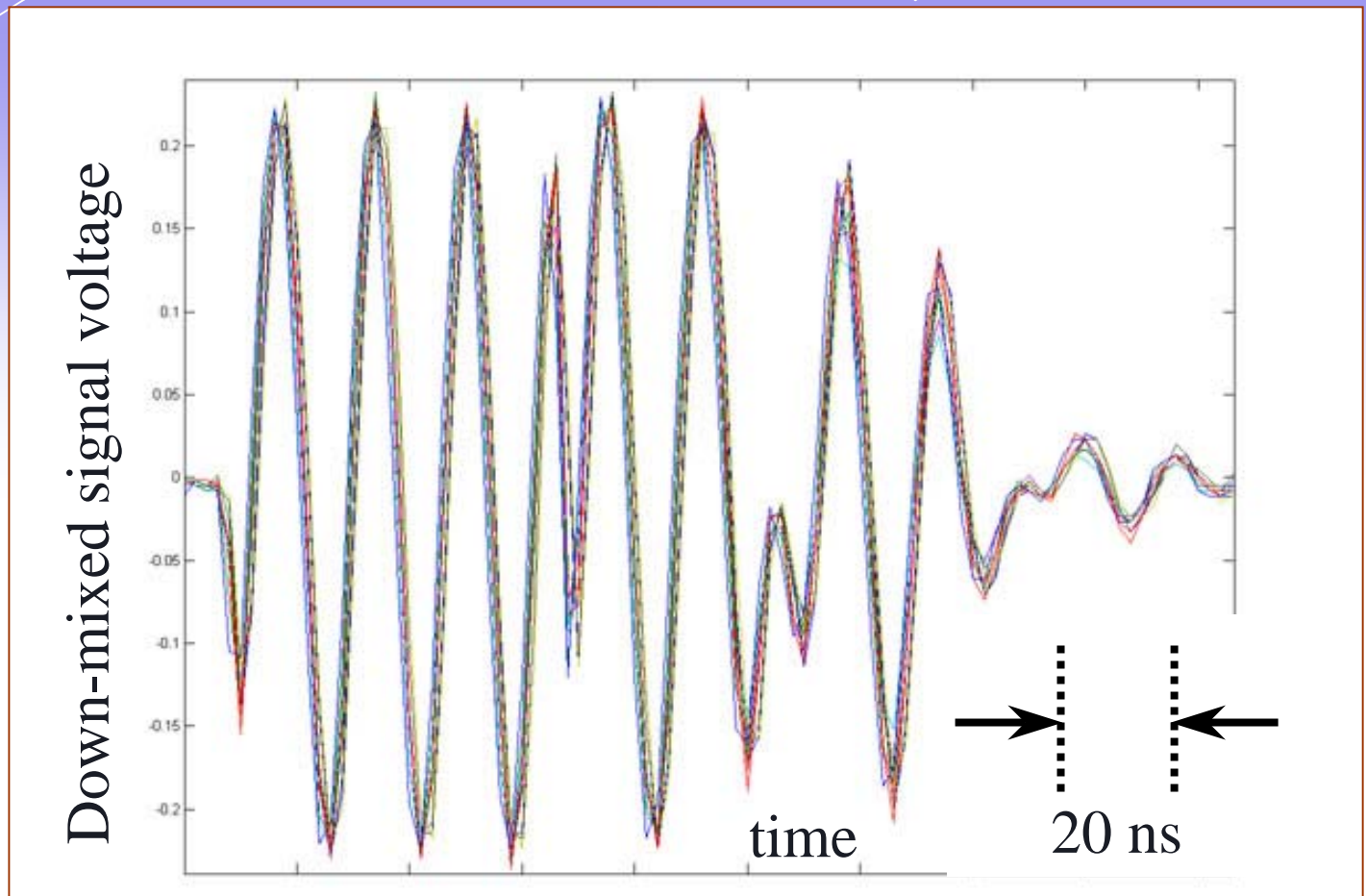
Dispersion in a coaxial cable broadens the signal to a full width of  $\sim 1$  ns.



# Phase detector signal path

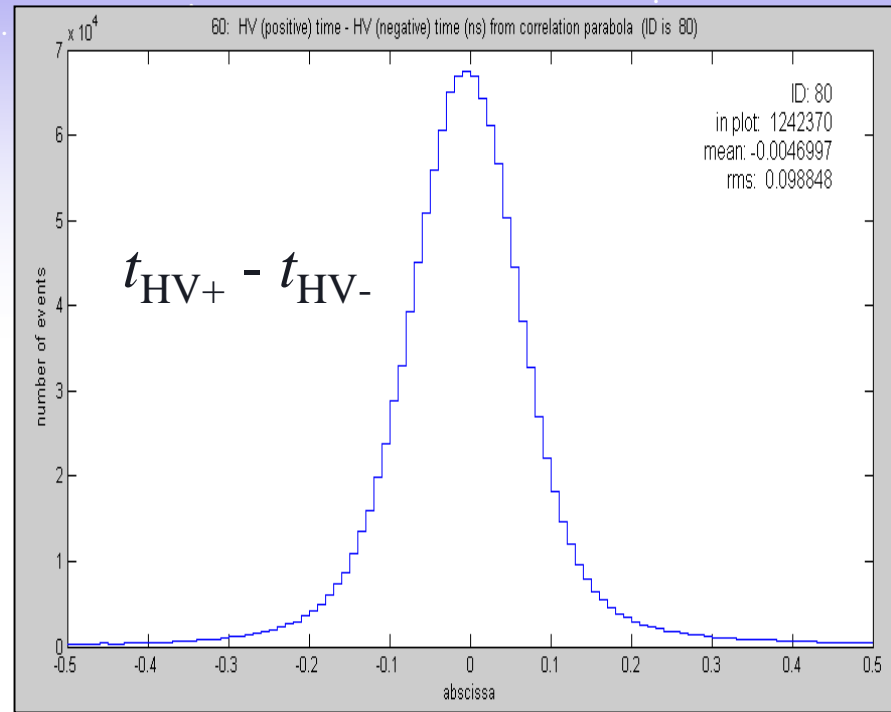
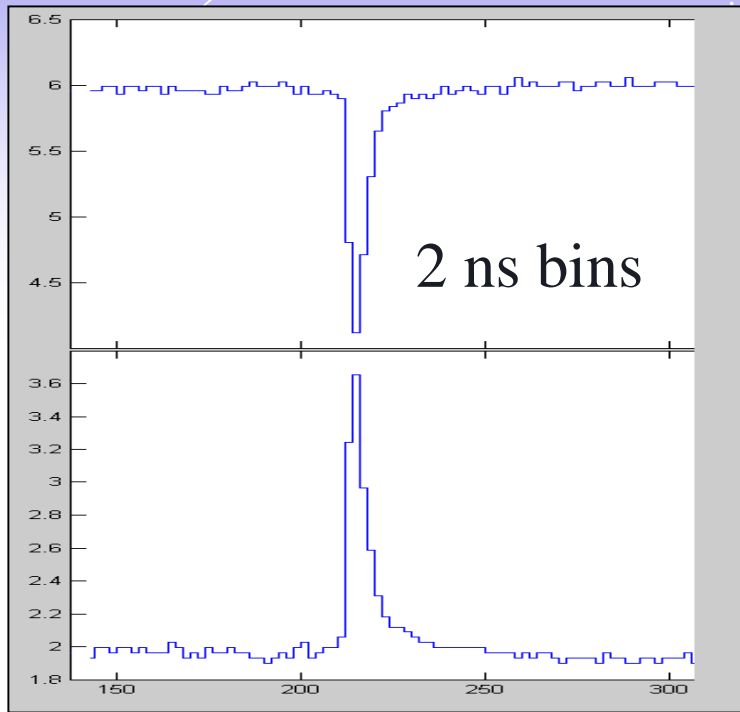


# Phase detector AØ data



We can probably determine the relative start times for each of the displayed signals with a precision of  $\sim 60$  ps. That maps into a bunch timing measurement accuracy of  $\sim 3$  ps.

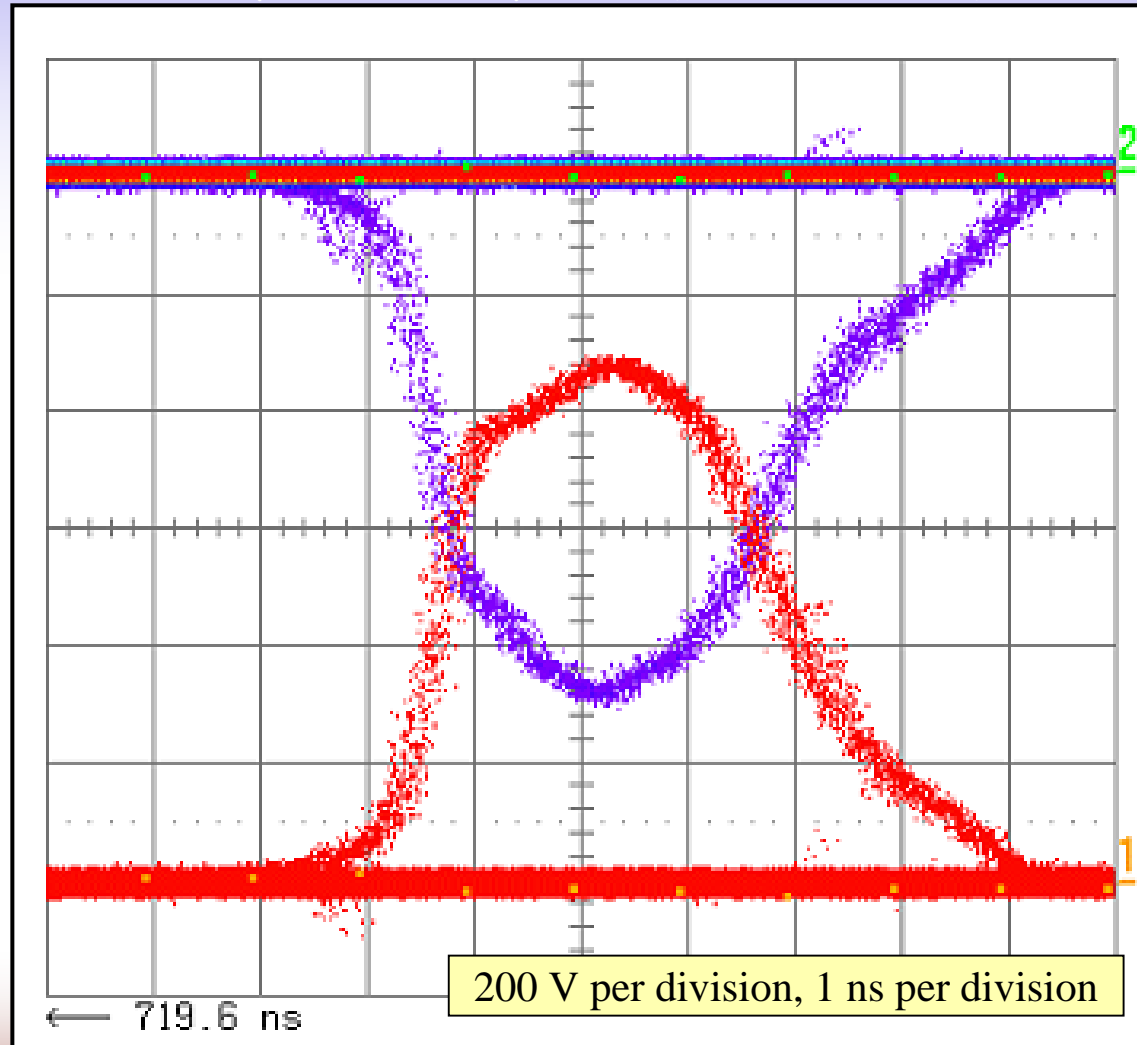
# FID HV pulser data



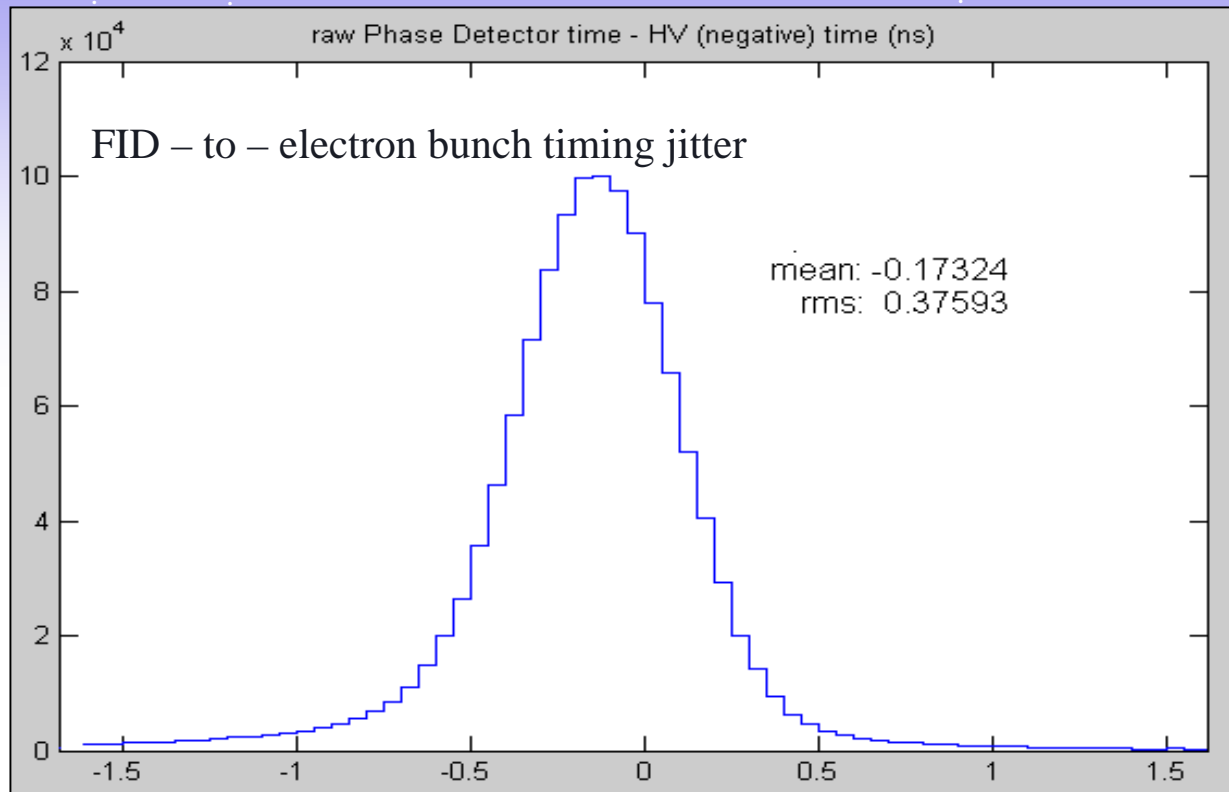
We can determine the relative times of the + and – kicker pulses with a precision of  $\sim 70$  ps if all the jitter is due to resolution. (Even better if some jitter comes from the FID itself.)

# FID HV pulse

$\pm 1$  kV pulses, 1 ns per division.



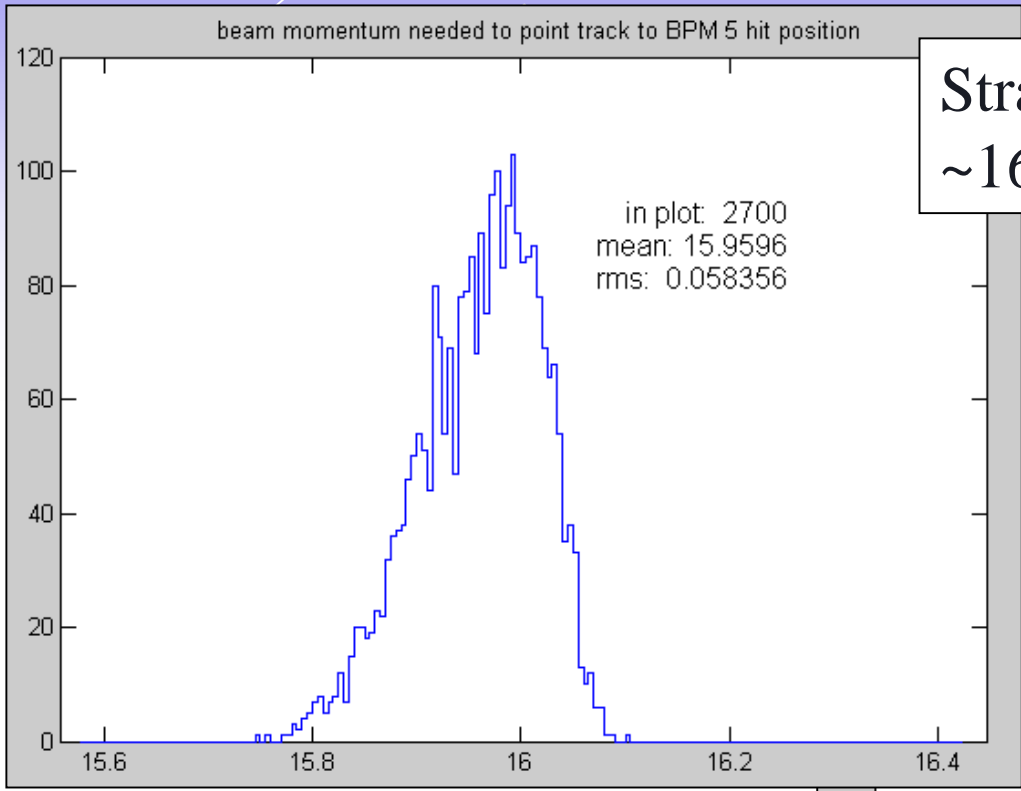
# FID – to – electron bunch timing jitter



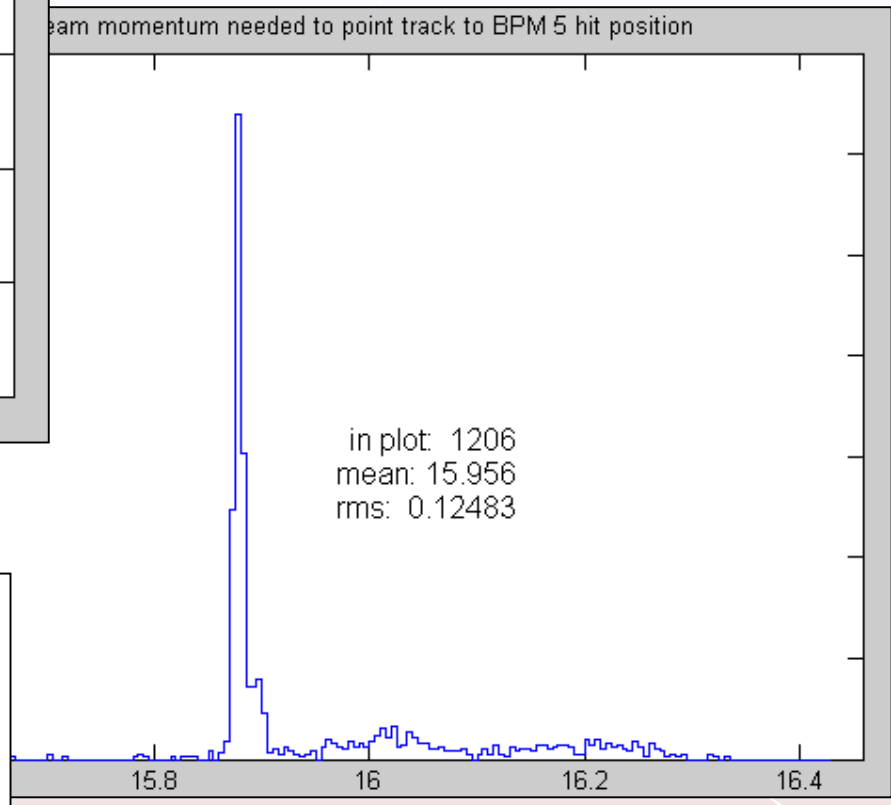
Jitter between raw phase detector signal and FID is  $\sim 375$  ps. If all of this is due to bunch arrival time variations it corresponds to  $\sim 18$  ps jitter in bunch arrival times. (Less if there are other sources of jitter such as the FID trigger circuitry.)



# AØ beam momentum



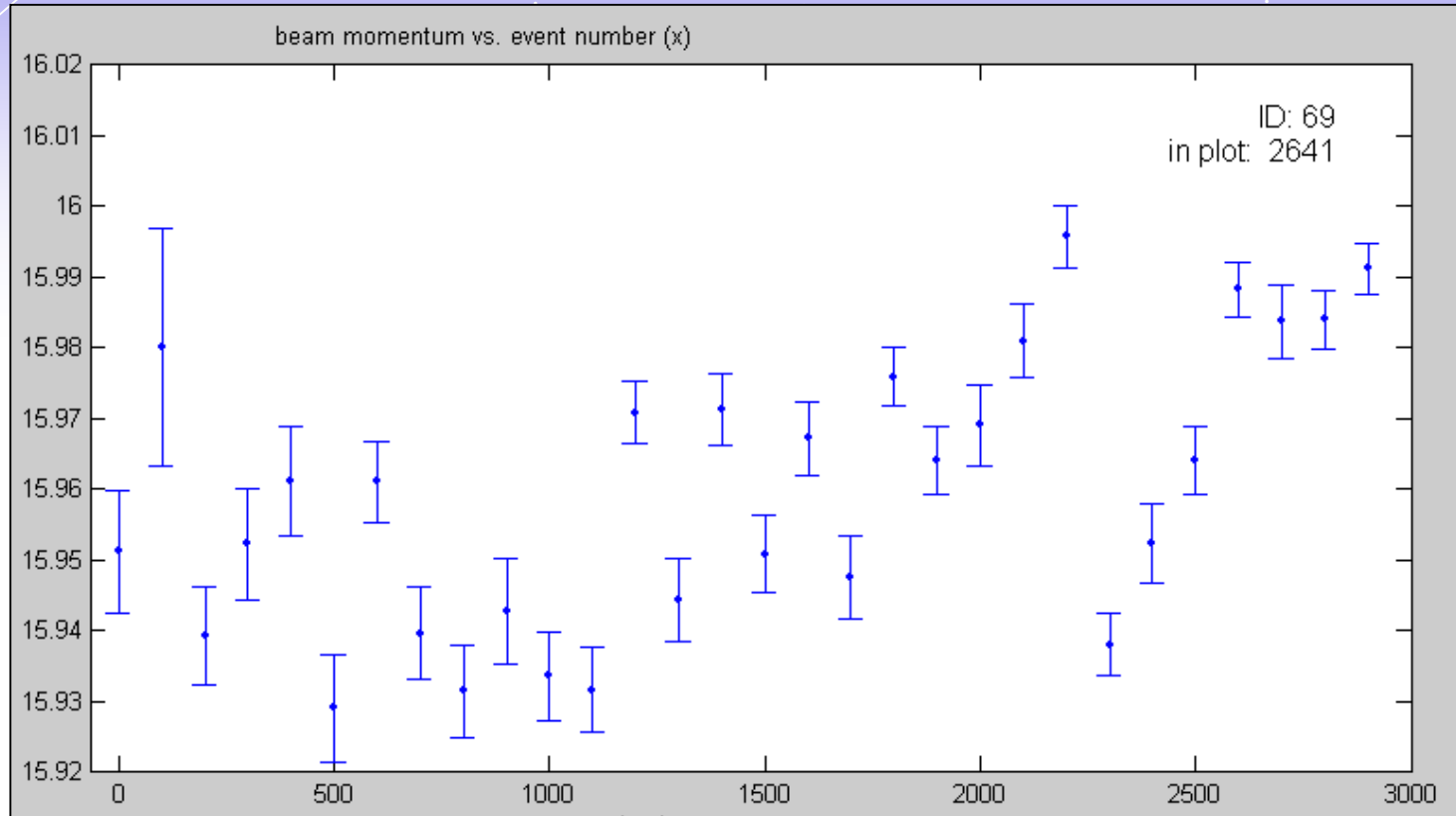
Straight-through run:  
~16 MeV, 0.3% RMS width



Everything on: we don't understand the origin of the anomalous tail yet.



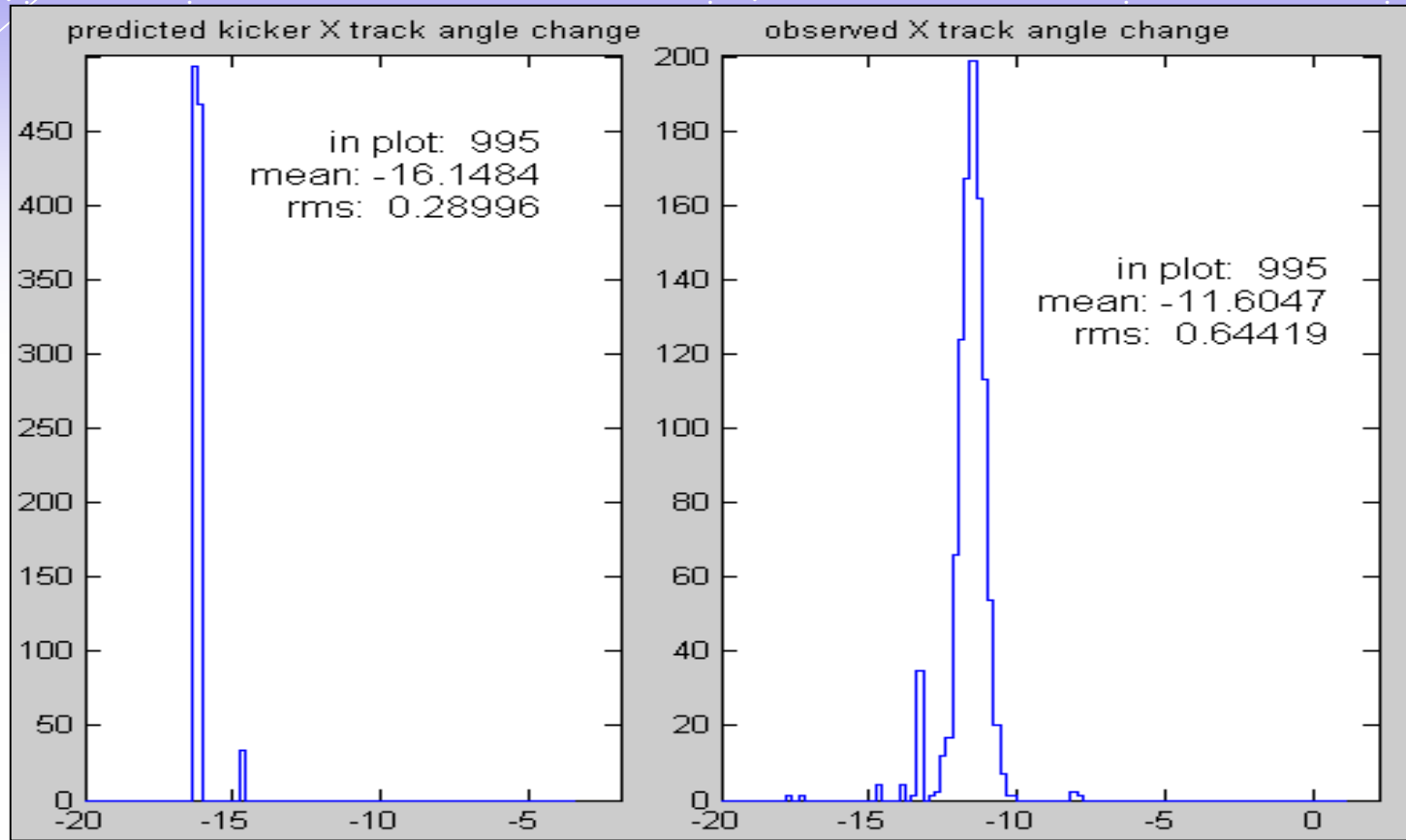
# AØ beam momentum



Straight-through run: average momentum per 100 events as a function of event number. It jumps around!



# Predicted vs. measured kick (mrad)



We have some overall scale factors to work up, as well as a few details associated with the corrector magnet.

# Why do this with a beam?

We can:

- test that the kicker really does what it is supposed to do, including problems from reflections and mistermiations.
- test devices where the kick cannot be measured easily as a voltage on an oscilloscope (magnetic devices, RF devices,...
- study electrode geometries



# AØ issues

- Low beam energy leads to sensitivity to small fringe fields
- Large kick angles are not characteristic of a 5 GeV beam, so geometrical issues will be different for the AØ and damping ring beams
- We need to understand kicker measurement sensitivities to the stability of AØ beam parameters better than we do at the present time.



# Near-term plans

- Understand systematics of time measurements
- Fine-tune the  $A\emptyset$  geometry used in event reconstruction
- Understand kicker measurement sensitivities to the stability of  $A\emptyset$  beam parameters better than we do at the present time
- Map out FID timing and amplitude stability
- Begin modeling realistic electrode geometries
- Investigate possibility of tests with other pulser technologies
- Investigate a reconfiguration of  $A\emptyset$ : redundant measurements; two phase detectors; higher precision BPMs; magnets with reduced fringe fields.
- etc.